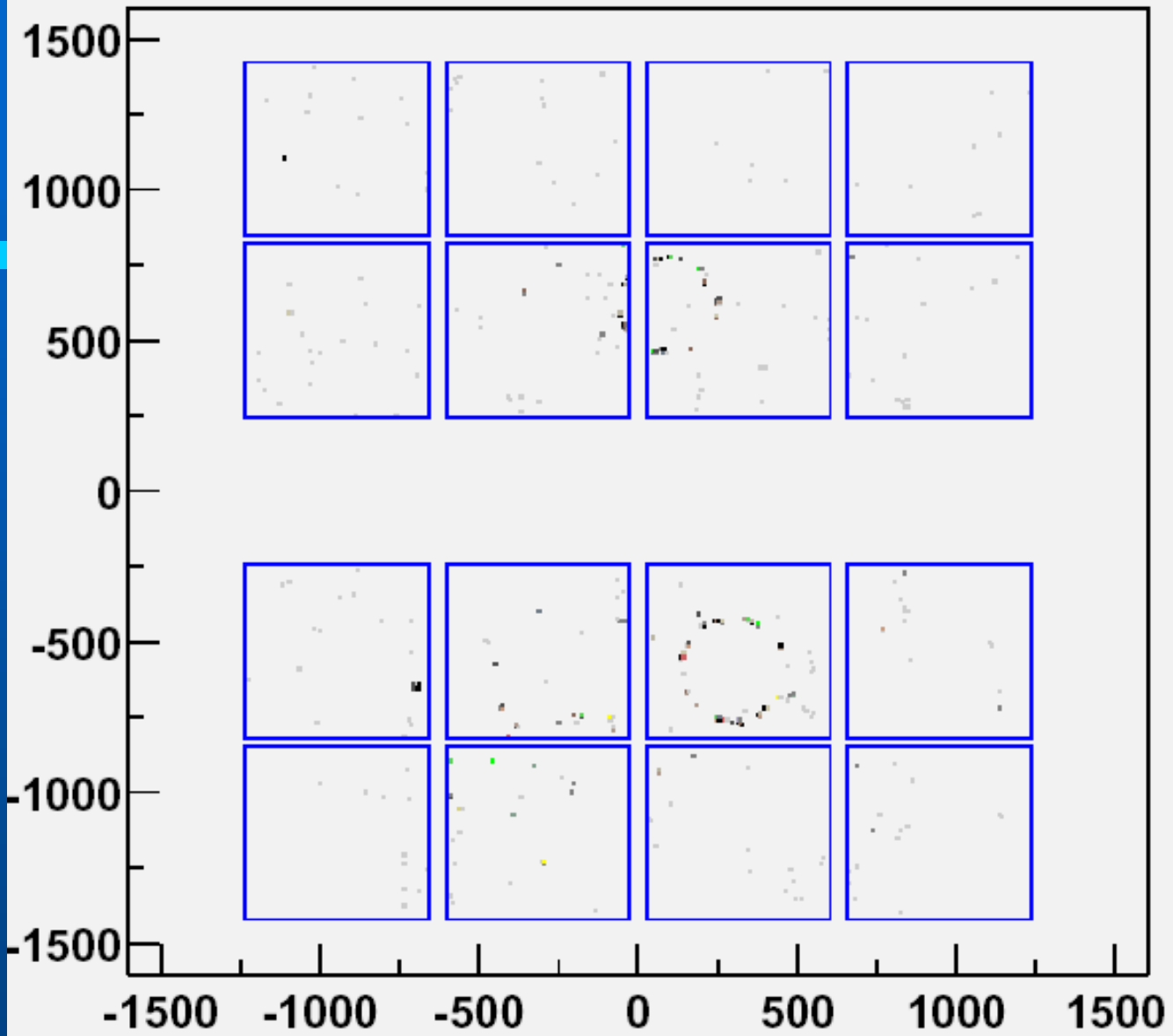
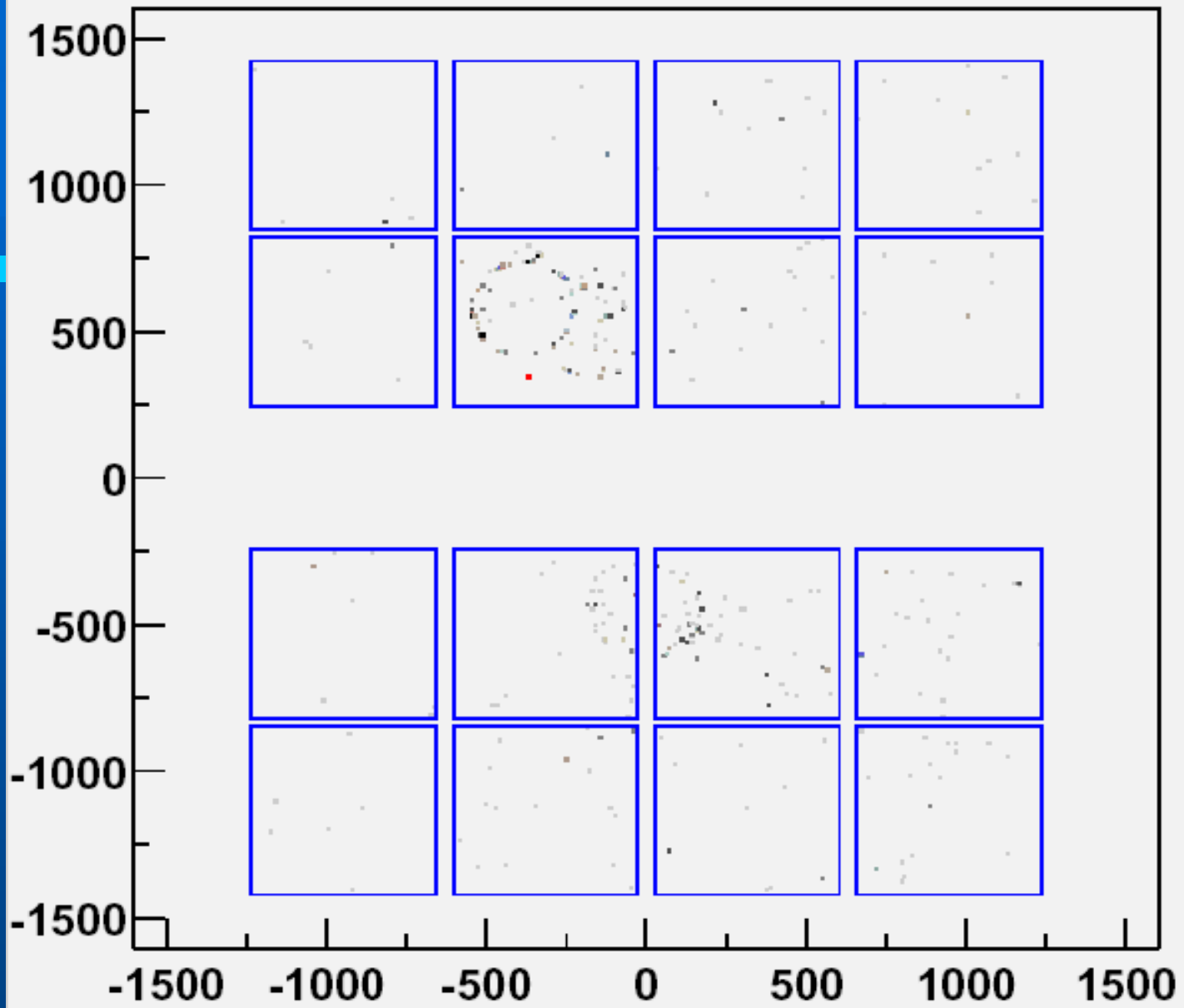


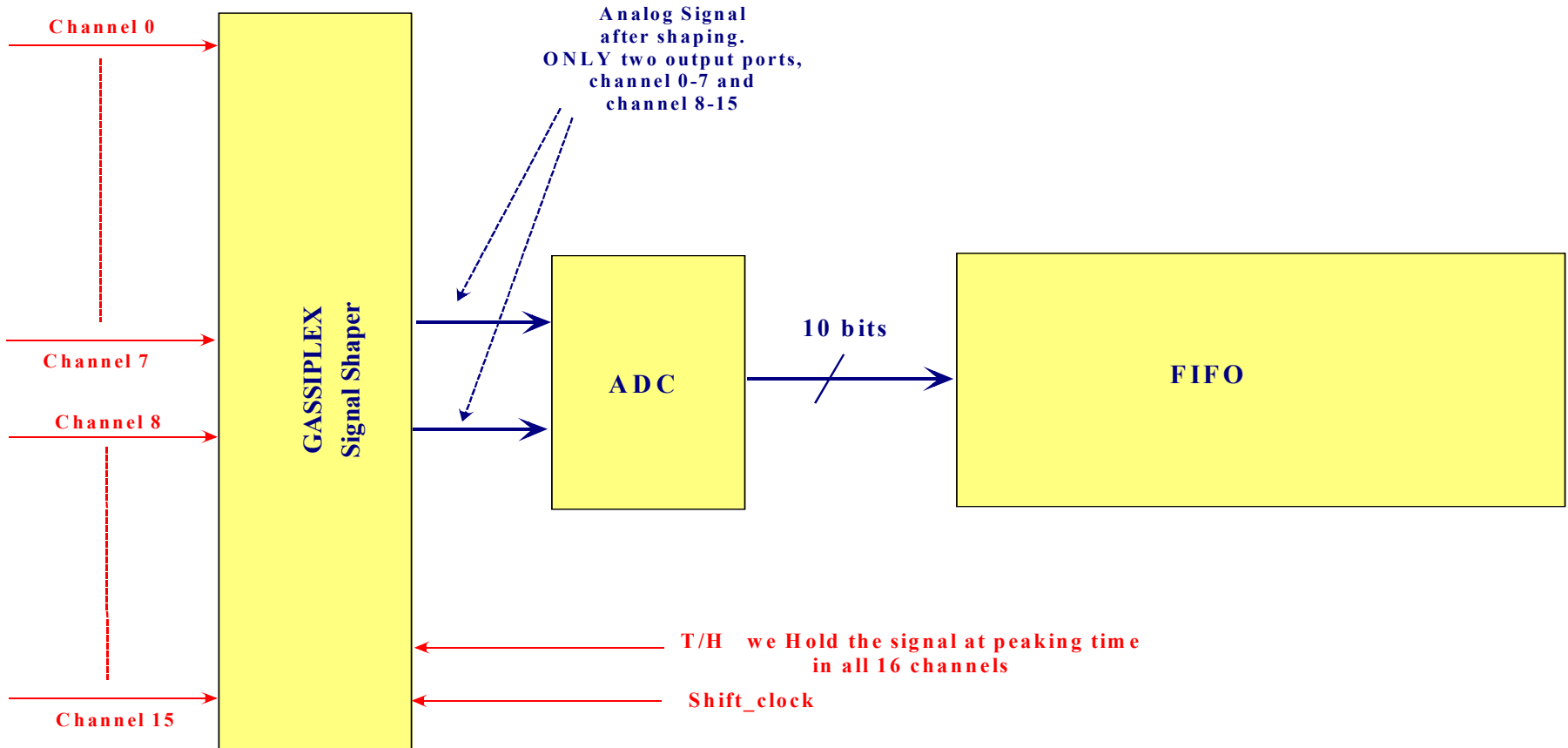
A simple and rapidly executable
way of getting rid of Halo events
as if they were noise.

Alberto A. Colavita



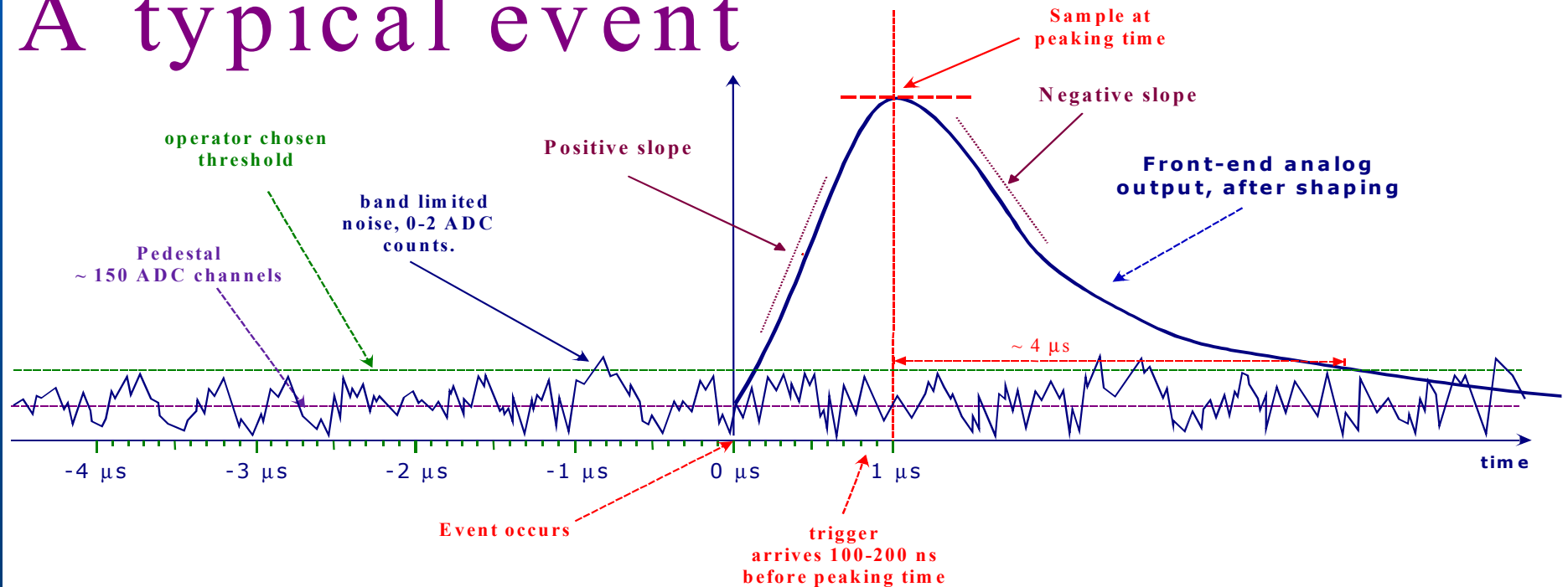


Schematic view of the presently installed front-end

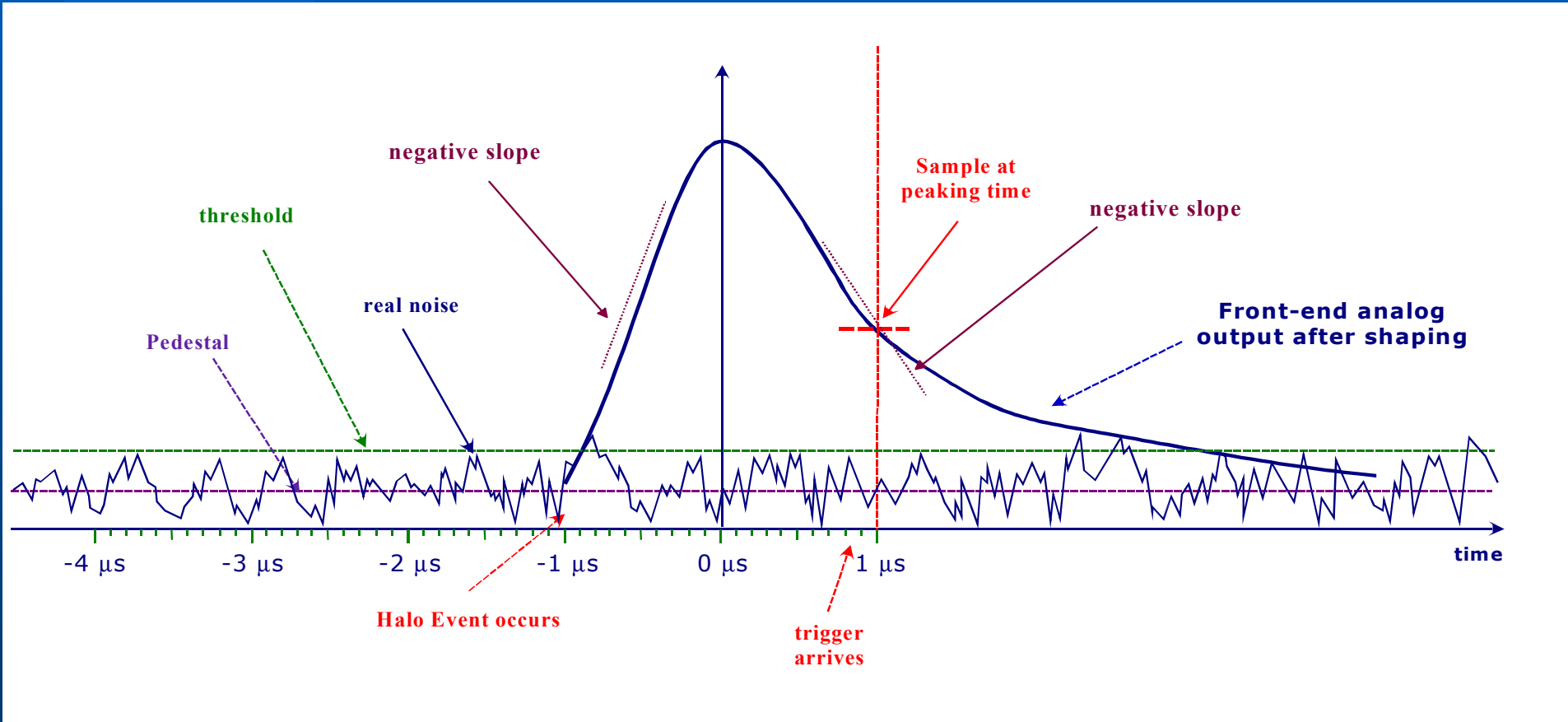


The shape of a normal signal of an event.

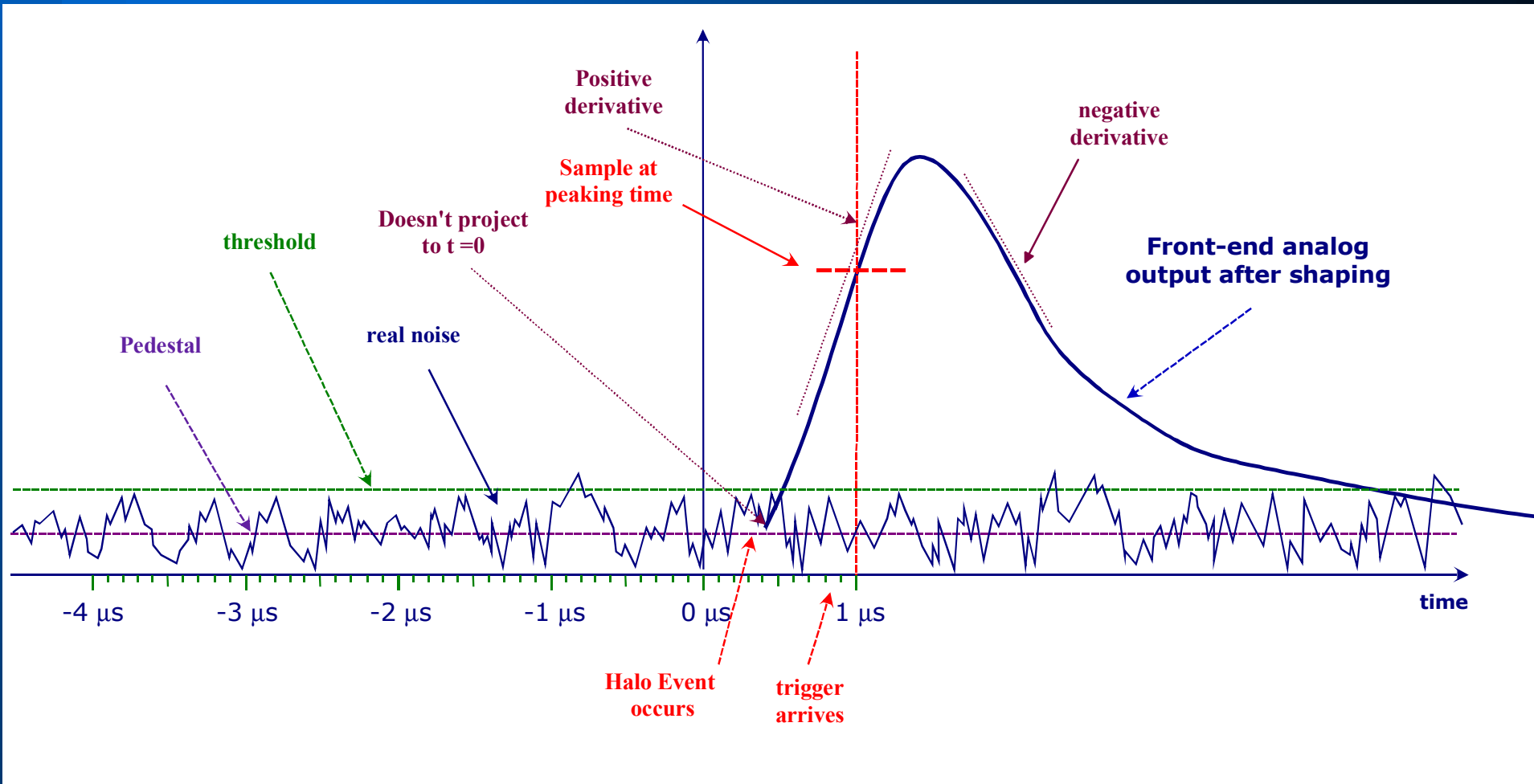
A typical event



Halo event, $t_0 < 0$



Halo event, $1 \mu\text{s} > t_0 > 0$



What separates Halo events from good events ?

- The only discriminating parameter is the “time history” of the signal.
- We need to memorize the past and part of the future.
- Detectors can be fast (PM) or slow (gaseous), in both cases history is the determining factor.

Upgrading 4 – Half Chambers

- ~ 21000 pixels (pads), 60 BORAs.
- To save the history of the signal we need to save at least ~ 10 - 60 samples per signal channel taken every ~ 100 ns.
- We need processing power in order to identify the Halo events from good events.
- We need better time definition to describe, without too much error, the start of the shaped signal.

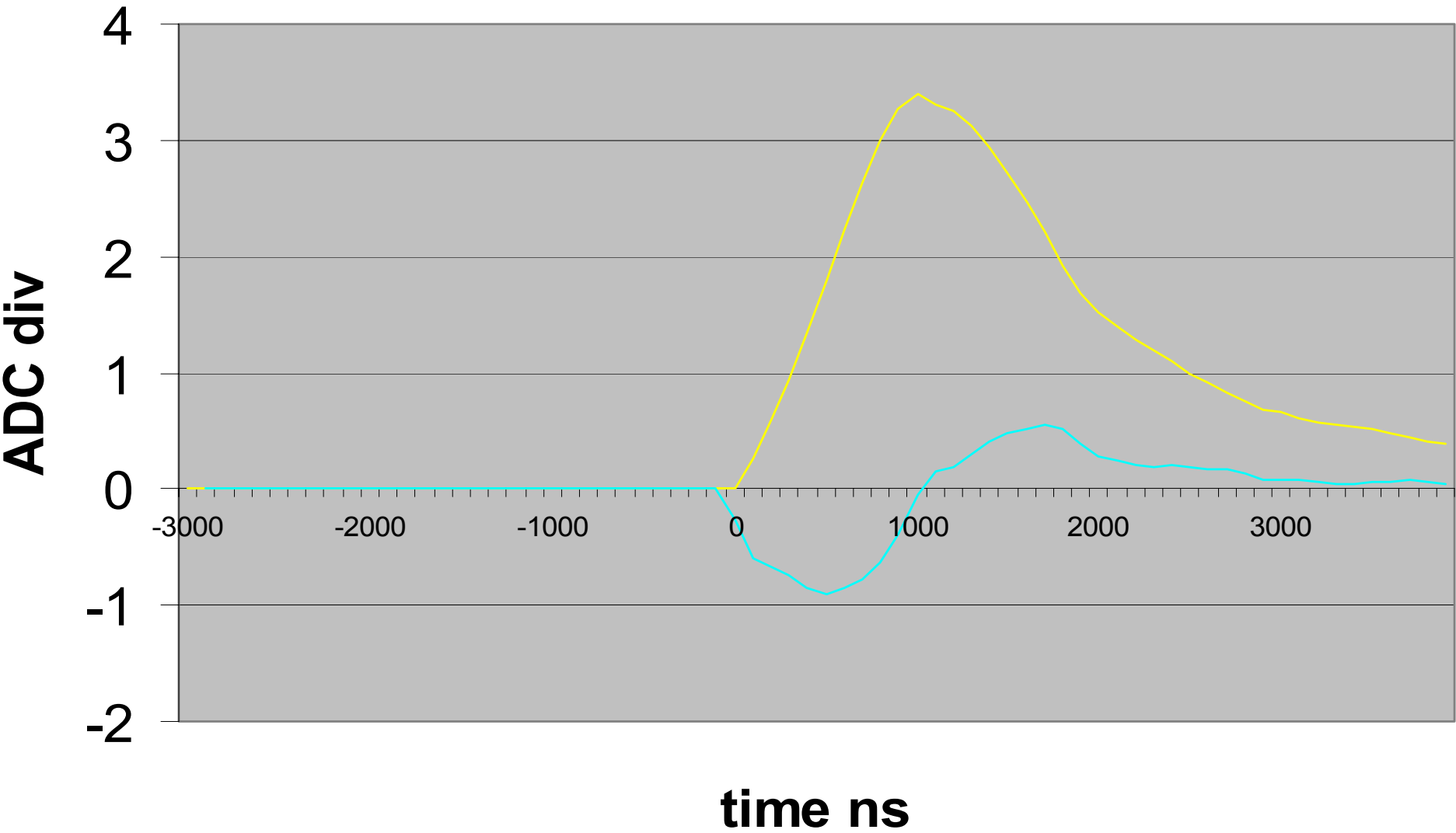
Two ways to pull the trick (a)

- **Replace slow gaseous detector and front-end with PMs:**
 - **Benefits and drawbacks.**
 - Great time definition ~ 15 ns.
 - Very expensive !!!!!
 - It needs new everything:
 - Optics
 - Electronics, although rather simple.
 - Mechanics. New mechanics precludes that the new system cannot be built when data-taking is under way.
- **We cannot work in parallel during data taking because of the many modifications**

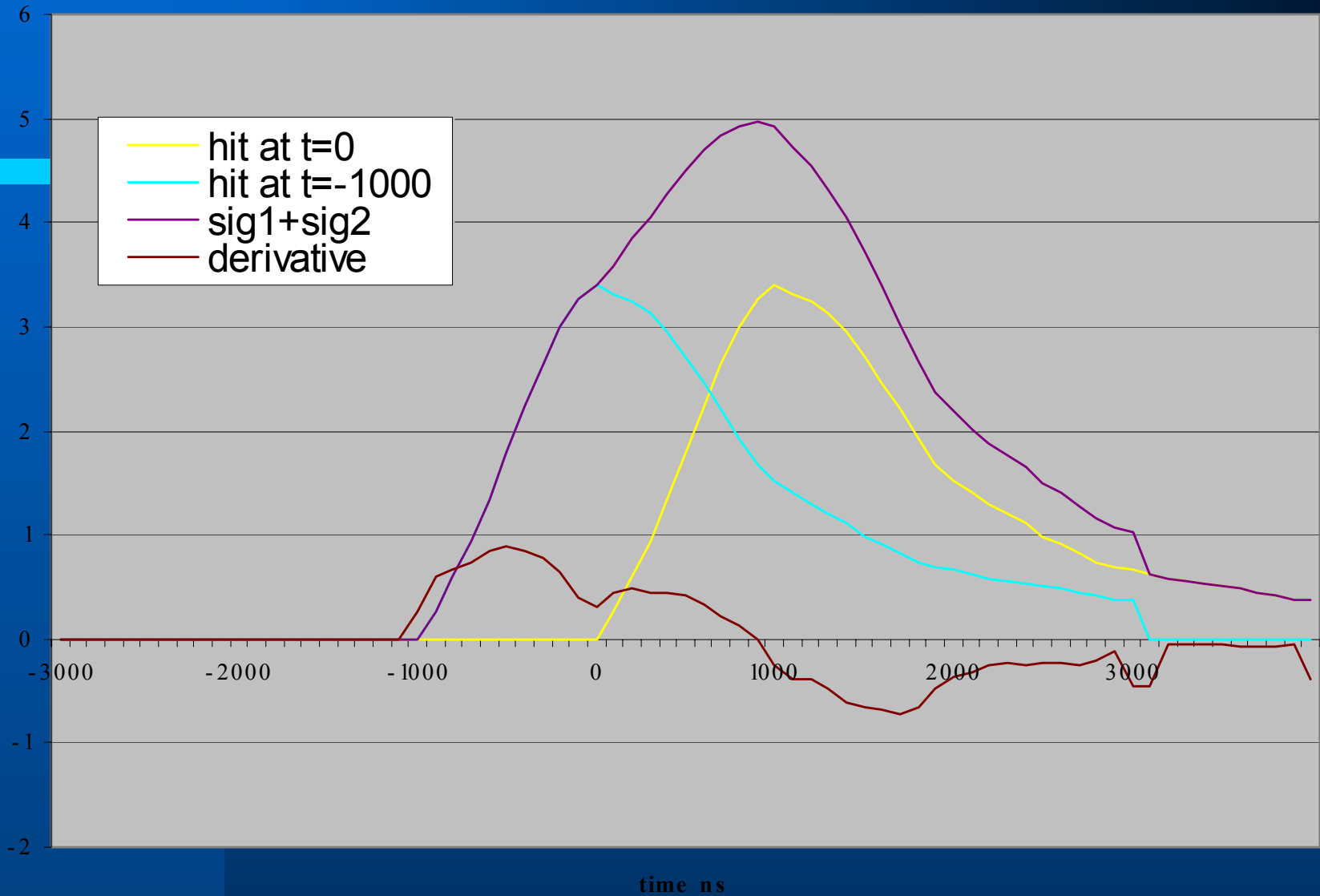
Two ways to pull the trick (b)

- **Keep slow detector design, add a large degree of local computing power (unprecedented amount)**
 - **Benefits and drawbacks.**
 - **Enough time definition that allows to get rid of 90% of Halo events.**
 - **Expensive, but cheaper than PMs !!!!!**
 - **It needs:**
 - **New electronics with ~10000 ADC and same amount of DSPs**
 - **No new Mechanics. Then, we can build the new BORAs while data taking. We can try to have by 2004 !!!**

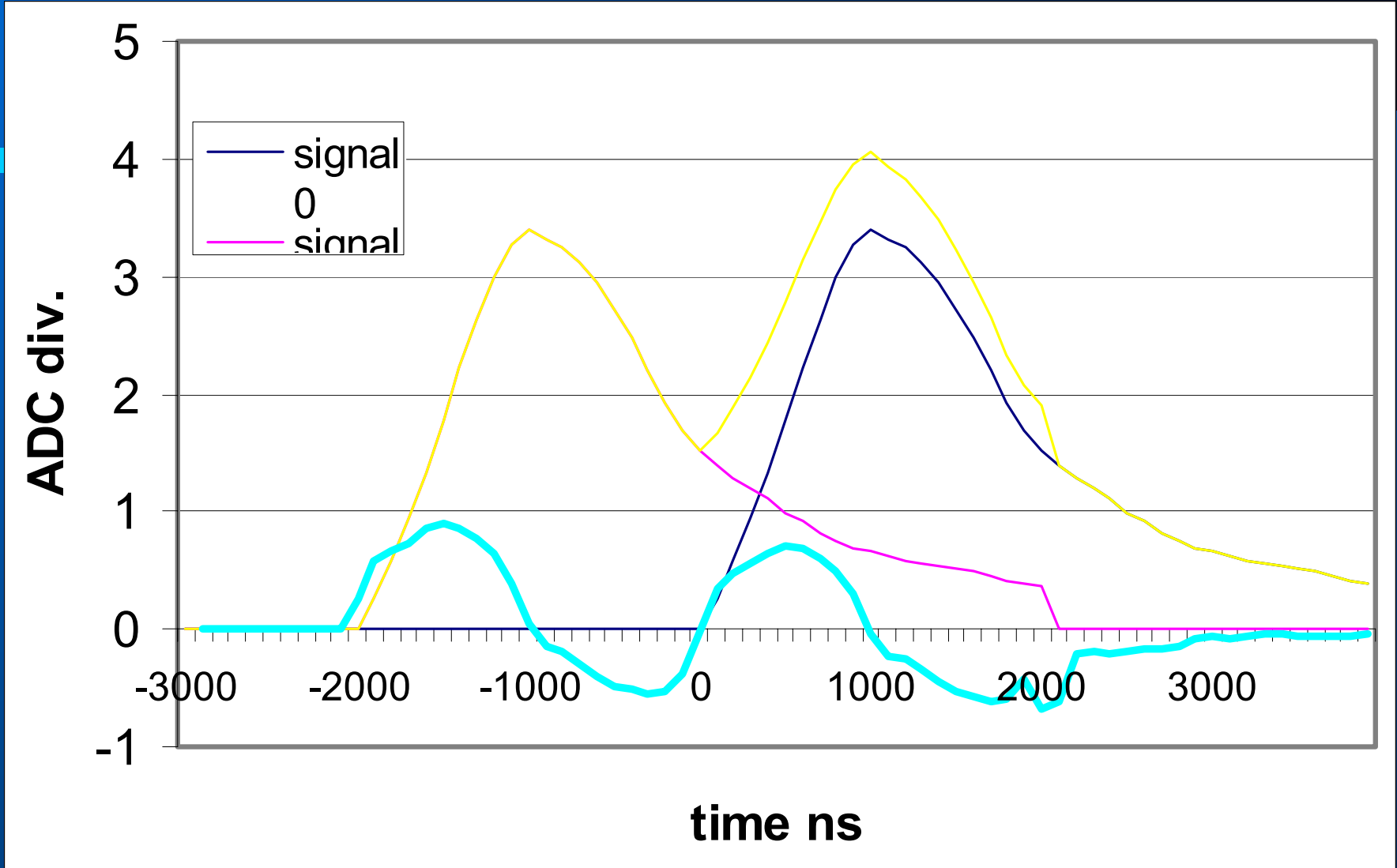
A typical signal and its derivative



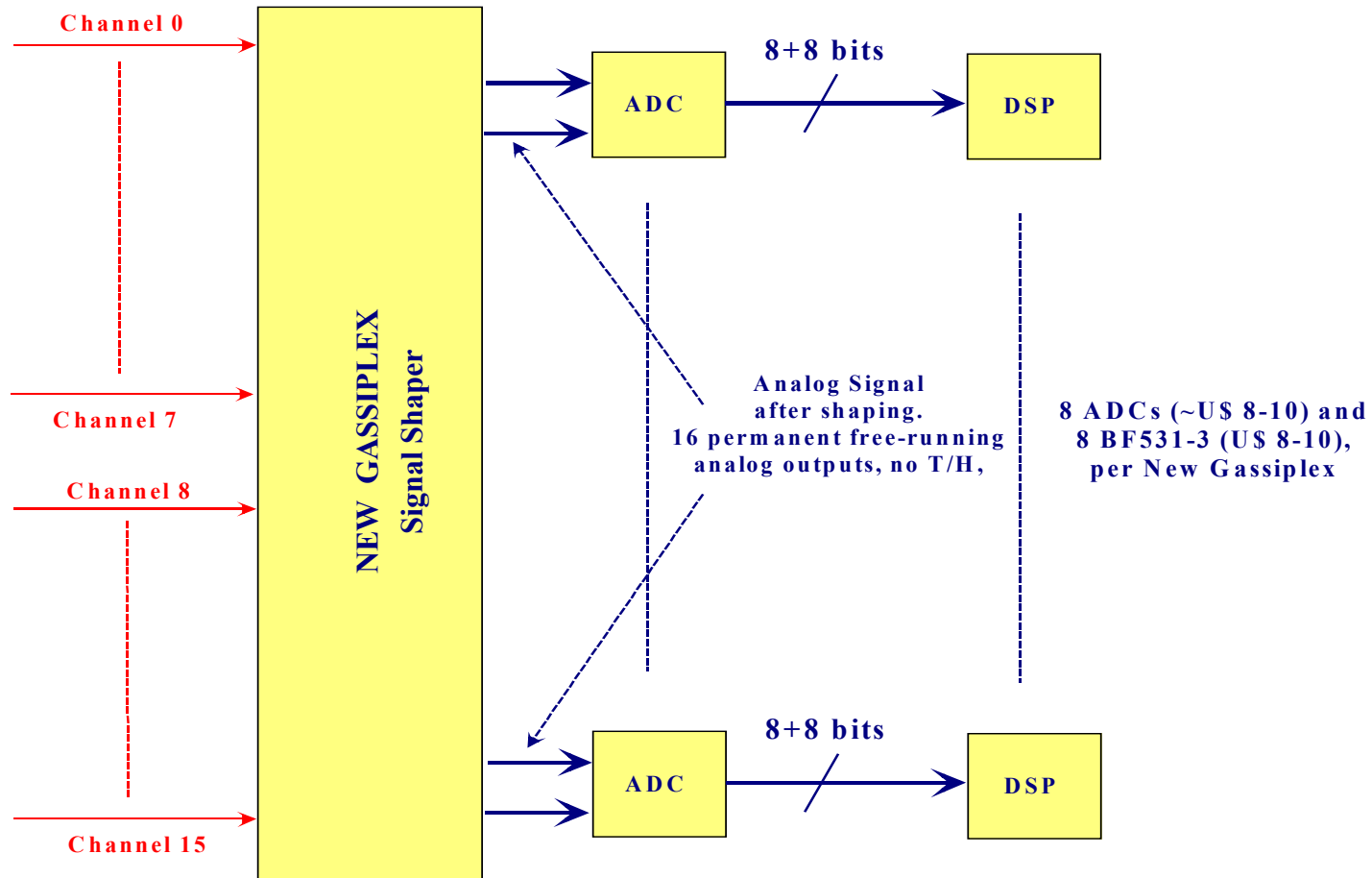
Sum and derivative of two signals (a)



Sum and derivative of two signals (b)



(b) New BORA



(b) Strategy for local data treatment

- **Sample every ~100 ns, place the 8-bit result into a circular buffer of at least 60 bytes deep. A BF531-33 DSP handles circular buffers using internal hardware. The internal memory is large enough for several k-samples within circular buffers. Use as much as possible the 4 internal, parallel MAC (Multiply Accumulate) units.**

(minimum, but no truthful) algorithmic Procedure

- Check if signal sample is below the threshold. Yes = Pad not hit.
- Was the sample taken at the maximum of the signal?
Yes = accept value,
No = Pad not hit.

Etc...

Time, personnel and funding constraints.

- **Time: for development and construction and software development of 60 new BORAs > 1 year.**
- **Personnel: at least 6 scientists with experience.**
- **Funds: roughly about 2 million euros (computed the American way). Expensive since it includes all NREC, even for 25% of the electronics of RICH-1**